

Exploring the post-reinforcement pause using drift-diffusion models

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BACKGROUND

- While playing on electronic gambling machines (EGMs) participants show increased reaction times (RTs) after positive outcomes^{1,2}
 - Post-reinforcement pause (PRP)
- Volatility is an important characteristic of popular EGMs³ (e.g., slot machines)
- The Volatile Kalman Filter (VKF) describes choice behaviour in volatile environments⁴

→ Here we present preliminary results of reanalysed RT data of an EGM study⁵ where we compared VKF modulated drift-diffusion models (DDMs) to covariate models in their ability to describe PRPs.

METHODS

Design

Electronic Gambling Machine⁵

- “Play slot machine with €20”
- $N = 46$ with 200 trials
- Possible actions (among others)
 - Place bet
 - Small (€0.20)
 - Big (€0.60)
 - Playing out the gamble
- Fixed task structure
 - All trial outcomes fixed
 - Difference in monetary outcome due to different betting behaviours

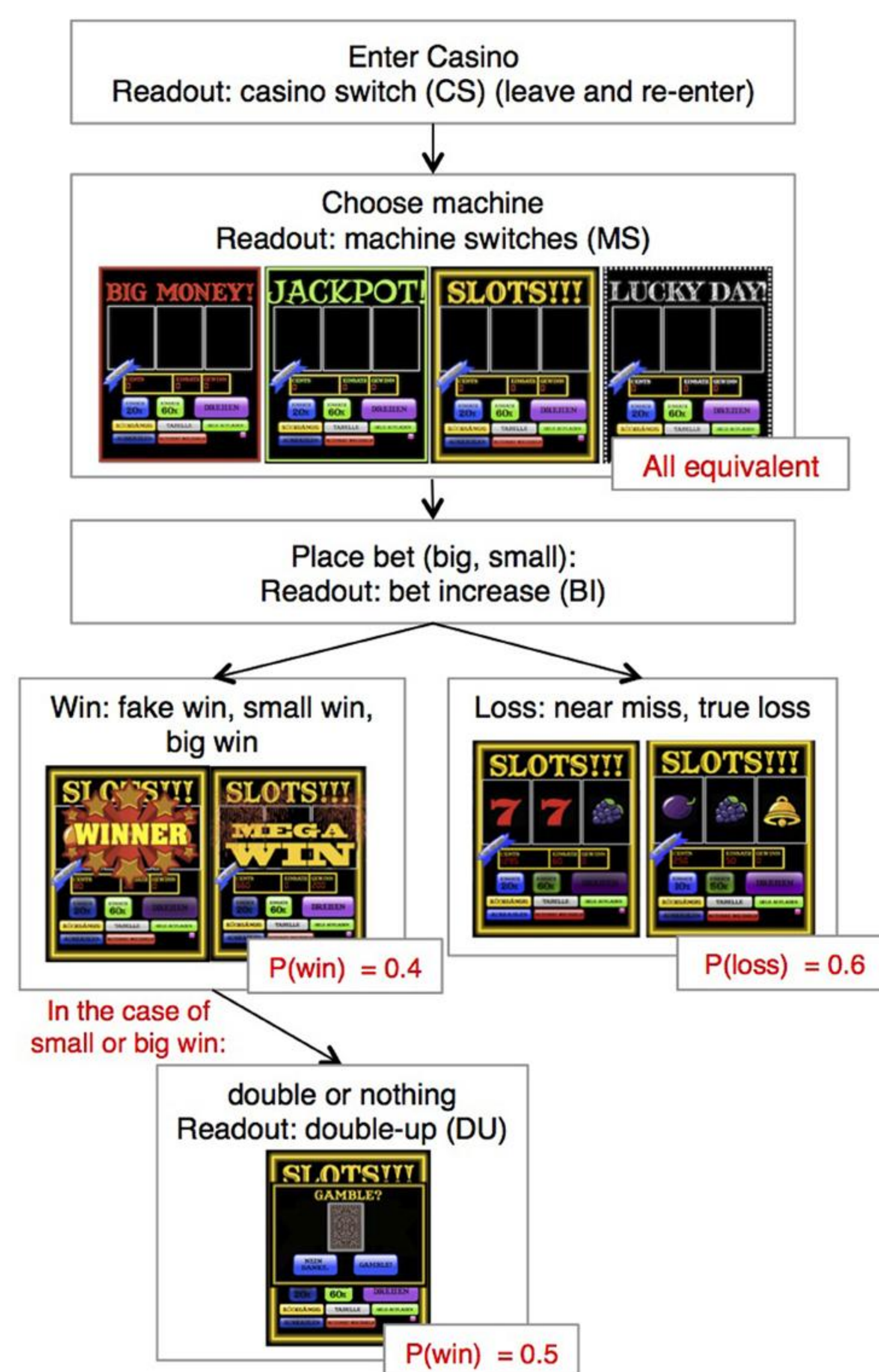


Figure 1. Structure of the Electronic Gambling Machine. From “A model-based analysis of impulsivity using a slot-machine gambling paradigm” by Paliwal and colleagues, 2014, *Front. Hum. Neurosci.* 8, p. 5.

Computational Modelling

Only trials with no other actions before betting or spinning the wheels used

RT cutoff: 150 ms < RT

Hierarchical Bayesian modelling in RStan⁶

Drift-diffusion model

- Non-decision time (τ)
- Boundary separation (α)
- Response bias (β)
- Drift rate (δ)

Volatile Kalman Filter

- Volatility learning rate (λ)
- Initial volatility (v_0)
- Outcome noise (σ^2)

Covariate model

- Covariate for each different trial type

RESULTS

Model-agnostic

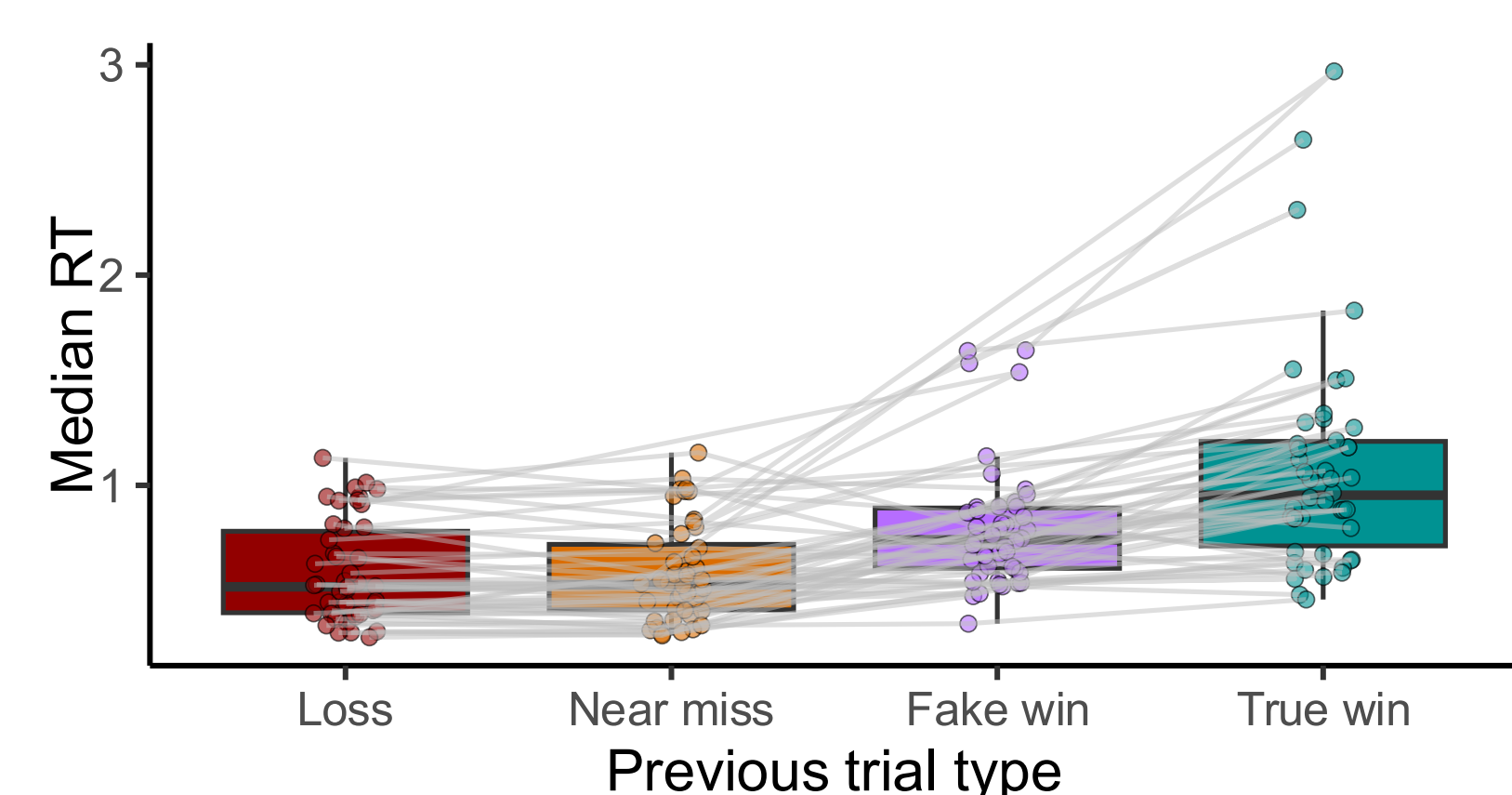


Figure 2. Observed RTs. The data provided extreme evidence for a difference in RT after true wins compared to any other outcome. The same was true for the difference between fake wins (losses disguised as wins) and loss outcomes (losses and near misses).

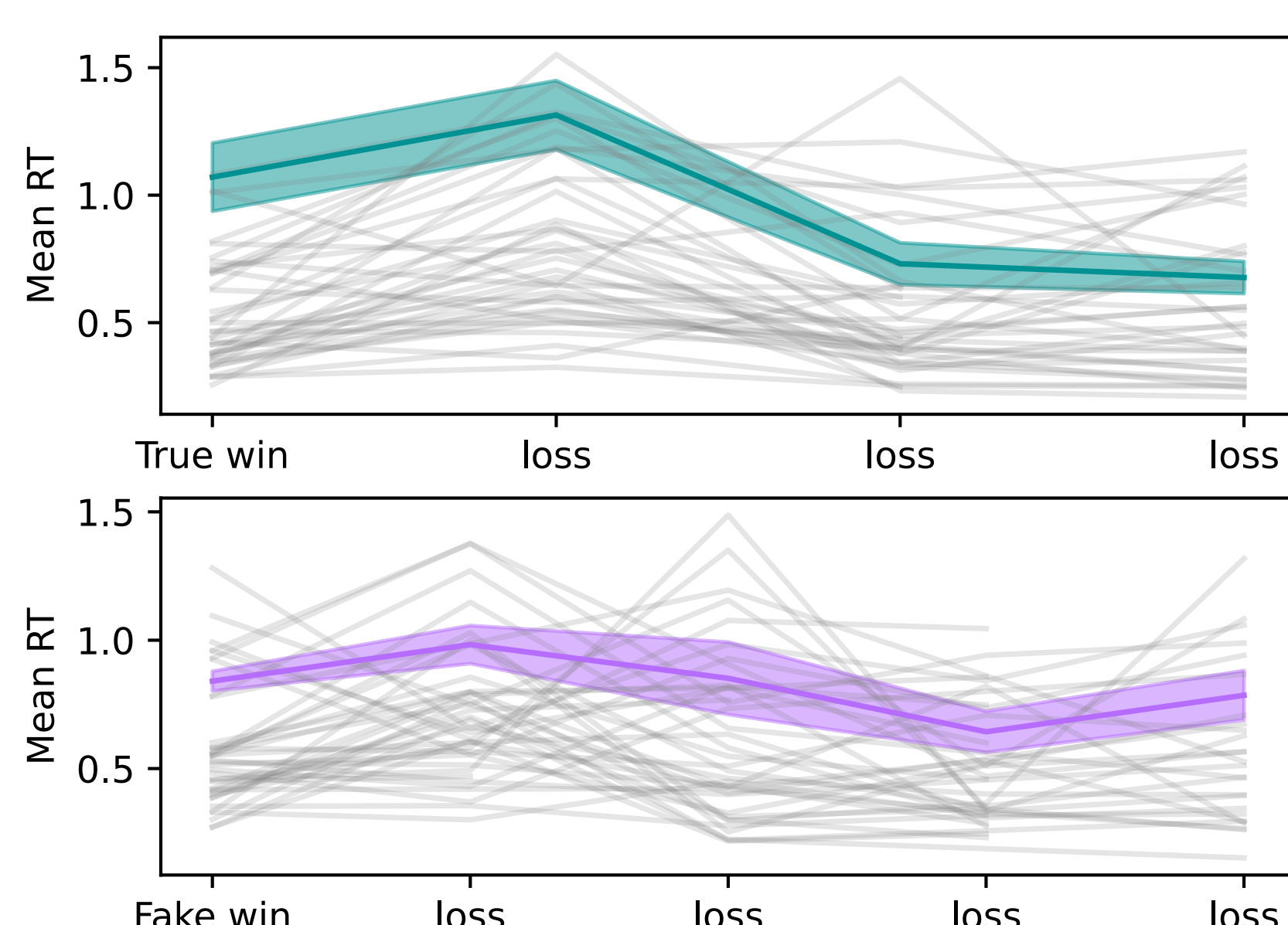


Figure 3. Simulated Volatile Kalman Filter. Several variables of the VKF compared to the average outcome of the EGM paradigm. $\lambda = 0.03$, $V_0 = 1.63$, $\sigma^2 = 1.16$

Figure 4. Sequenced Outcomes. Bold lines show the mean across participants ($\pm$ SEM), grey lines represent the mean within participants.

RESULTS

Model-based

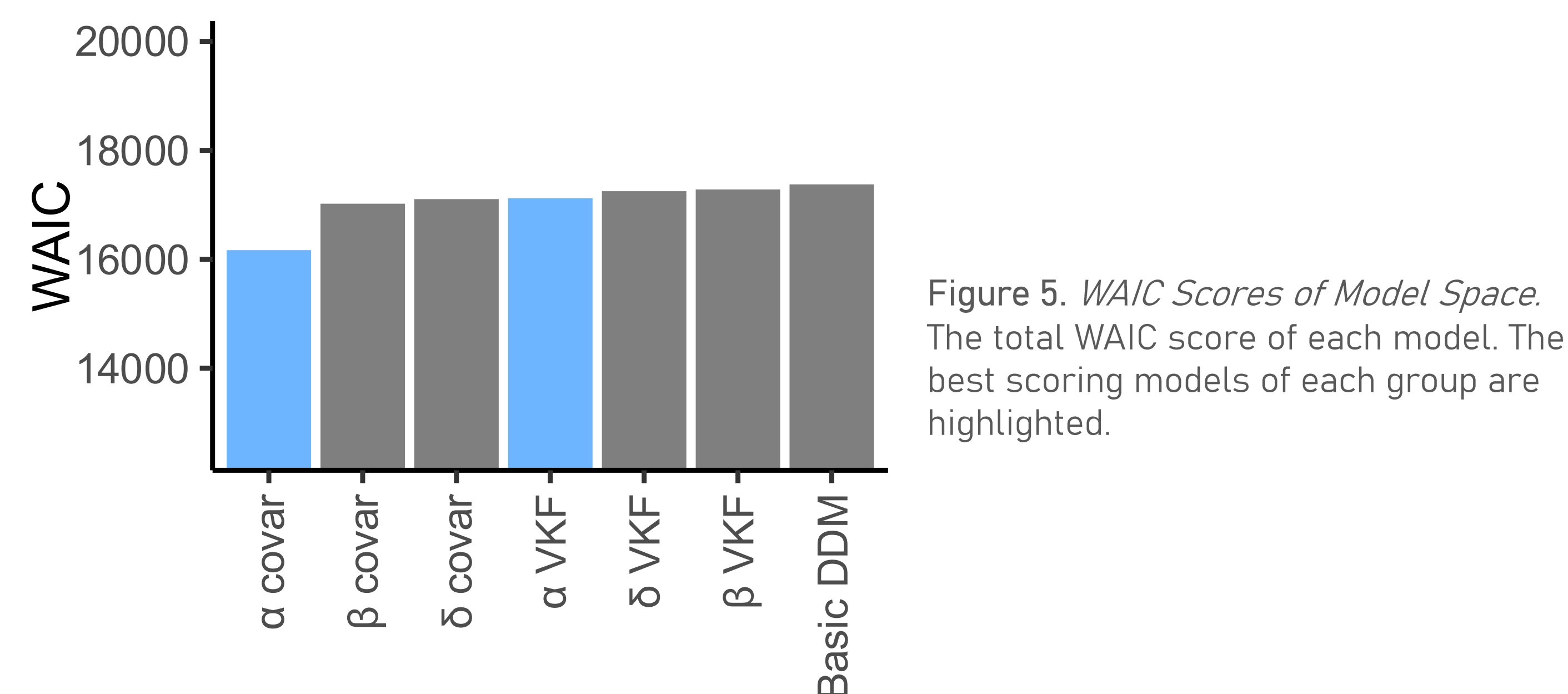


Figure 5. WAIC Scores of Model Space. The total WAIC score of each model. The best scoring models of each group are highlighted.

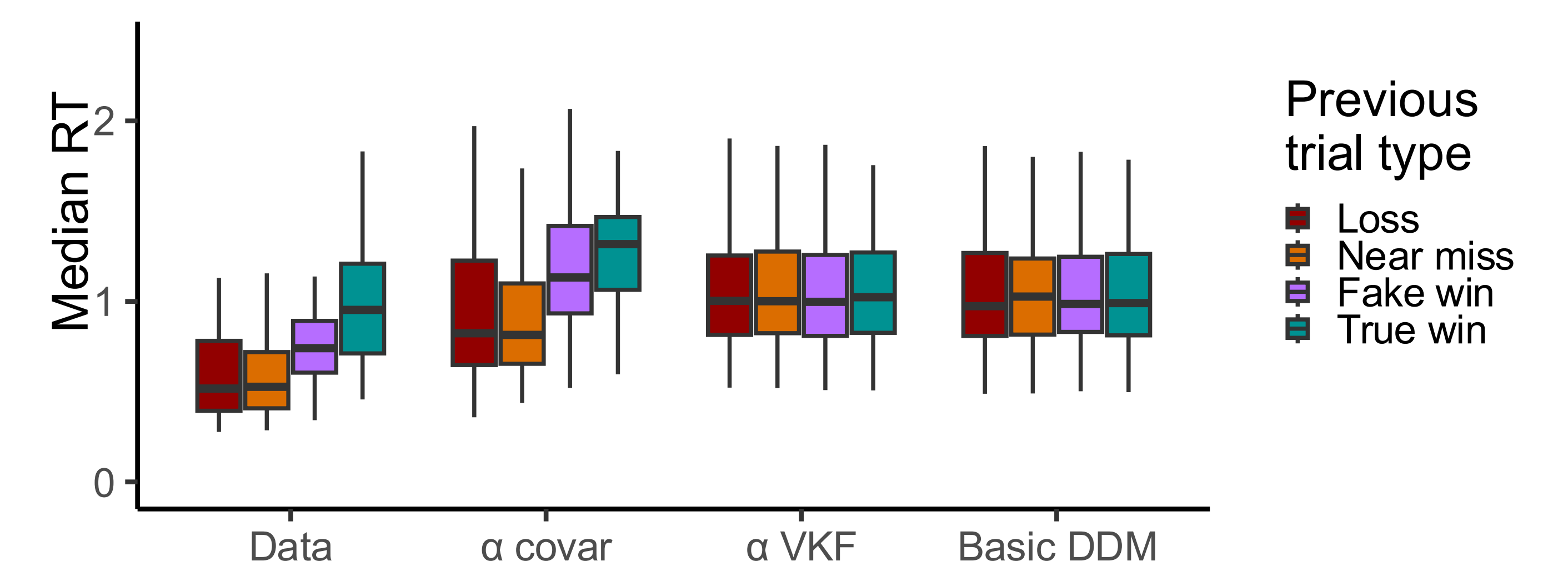


Figure 6. Posterior Checks of PRP Effect. Data simulated ($N_{sim} = 50$) with the basic DDM showed no effect of the previous trial type on the RT. The same was true for the VKF modulated DDM. The covariate model was able to replicate the PRP effect. Note that all models are all slower than the observed data (“Data”; see Figure 2).

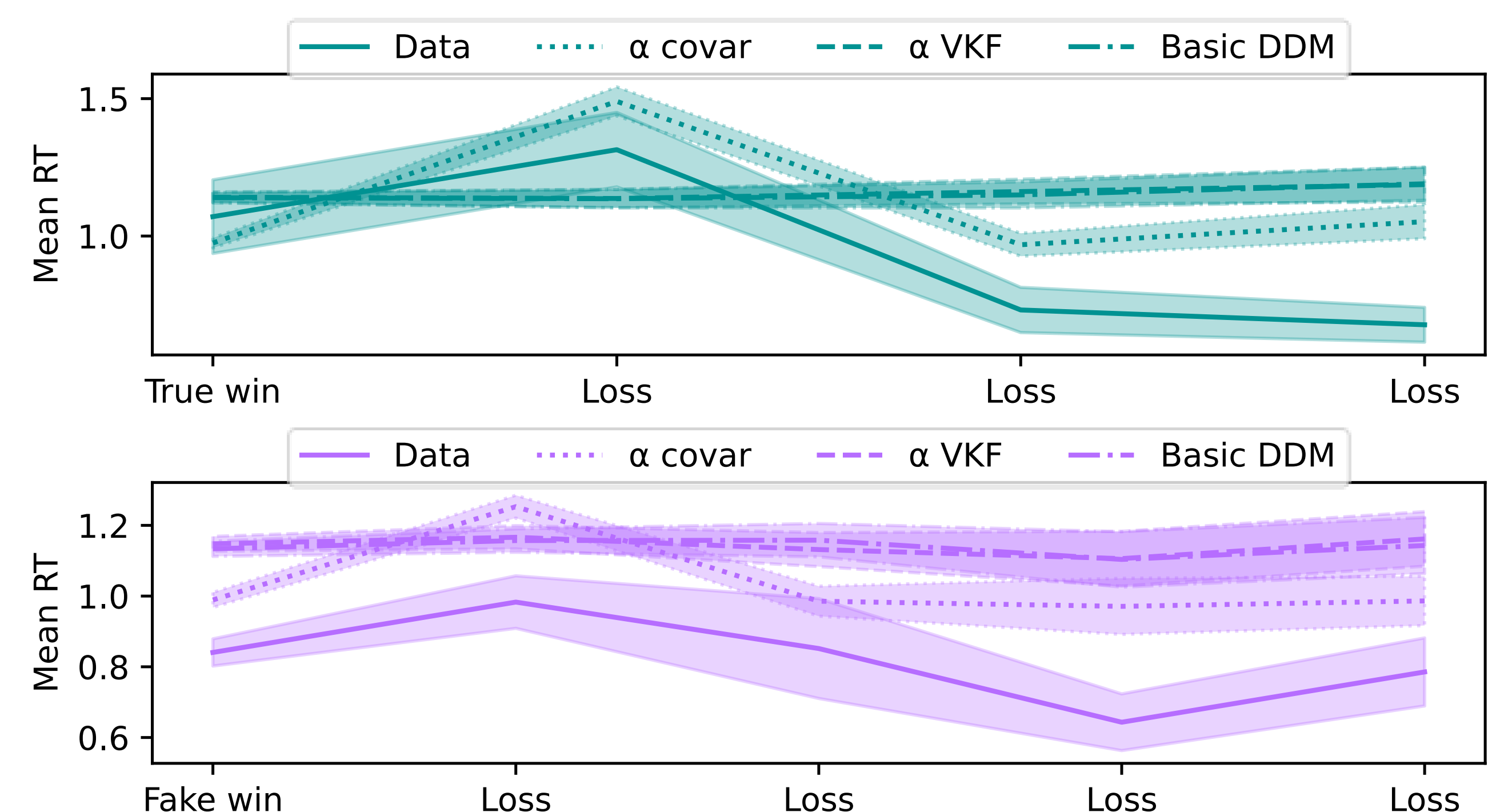


Figure 7. Posterior Checks of Sequenced Outcomes. The covariate model was able to replicate the pattern of the observed data (“Data”; see Figure 4). RTs simulated by the VKF modulated DDM and the basic DDM did not change over time.

CONCLUSION

Post-reinforcement pause

- Observed in the EGM study of Paliwal and colleagues⁵
- Appeared to be best captured by modulating the boundary separation
 - Increased caution after win
 - Might be related to loss chasing^{7,8}
- Not explained by only volatility prediction error

Next steps

→ Full models

- Modulators for all DDM parameters in one model

→ Further explore VKF calculations in DDM

- Volatility
- Mean uncertainty (i.e., the expected outcome)

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